

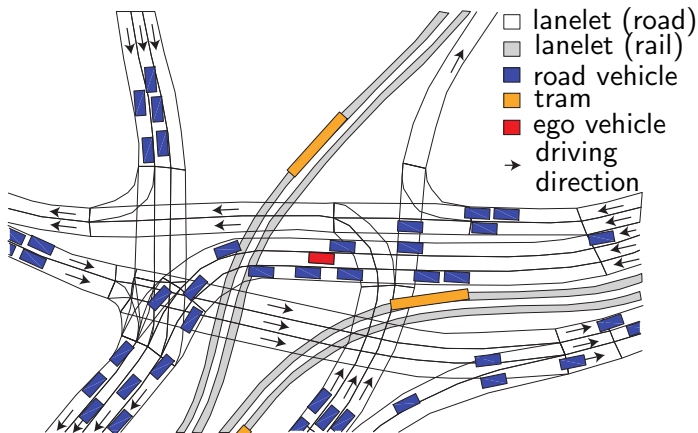
Traffic Scenarios for Benchmarking

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CommonRoad: Composable benchmarks for motion planning on roads [1]



[1] M. Althoff, M. Koschi, and S. Manzing, "CommonRoad: Composable benchmarks for motion planning on roads" in Proc. of the IEEE Intelligent Vehicles Symposium, 2017, pp. 719-726.

- How to get scenario data? Automatically?
 - Manual creation (hand-crafted)
 - Data from maps, e.g. Netconvert (SUMO) or [1]
 - Data from recorded traffic, e.g. NGSIM
 - Data from vehicles equipped with sensors
 - Other elegant solutions?

- Contact me for further details: `markus.koschi@tum.de`

[1] A. Artunedo, J. Godoy, and J. Villagra, "Smooth path planning for urban autonomous driving using OpenStreetMaps," in Proc. of the IEEE Intelligent Vehicles Symposium, 2017, pp. 837-842.