

# Cyber Physical Systems Seminar: Safety and Performance of Compliant Robots

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TU München

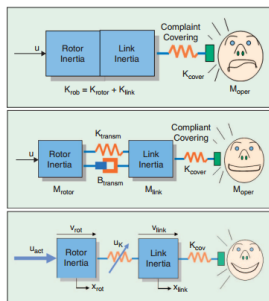
1. Jul. 2016

# Safety and Performance of Compliant Robots

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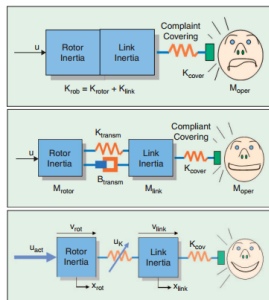
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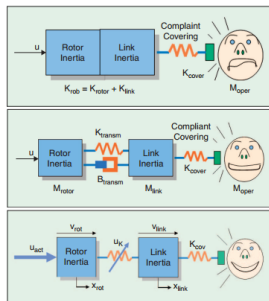


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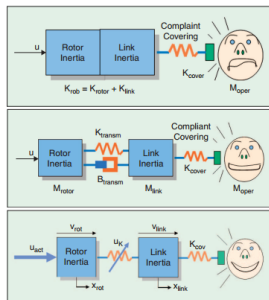
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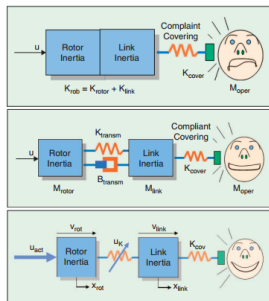
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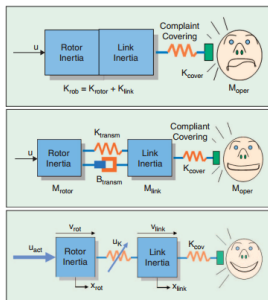
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**Starting reference:** [1] Bicchi, A.; Tonietti, G., "Fast and "soft-arm" tactics [robot arm design]," Robotics & Automation Magazine, IEEE , vol.11, no.2, pp.22,33, June 2004.